JACKAL[™] UNMANNED GROUND VEHICLE



SMALL. FAST. RUGGED. DRIVE RESEARCH FORWARD



READY TO GO RIGHT OUT OF THE BOX

With an on-board computer, GPS and IMU fully integrated with ROS, Jackal has out-of-the-box autonomous capability. With wireless connectivity via Blue-tooth and WiFi, Jackal is ready to go as soon as you turn it on!

MADE FOR THE GREAT OUTDOORS

Jackal's chassis is made entirely from welded aluminum and provides IP65 protection when the main bulkhead is sealed (optional). The high torque 4x4 drivetrain gives Jackal maximum traction, with enough on-board power available to traverse obstacles or unconsolidated terrain.

SMALL SIZE, BIG CAPABILITY

Swap payloads off Jackal's customizable mounting plate. As with all Clearpath robots, Jackal is compatible with many robot accessories to quickly expand your research and development. Additionally, users receive end-toend visibility of Jackal's operation with the comprehensive ROS API.

A FEW OF THE INNOVATIVE FIRMS WHO USE OUR ROBOTS



UNIVERSITY OF

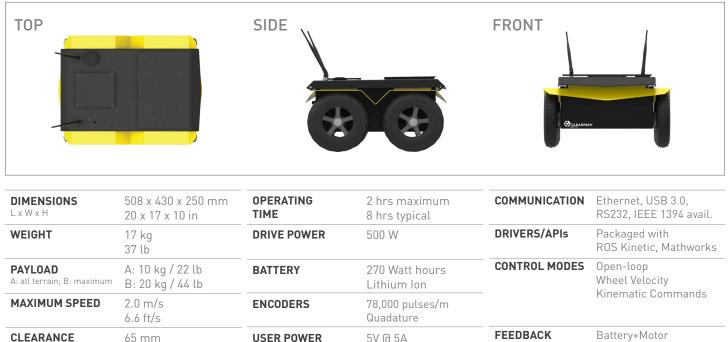
Carnegie Mellon University



Contact us today for pricing and a free 30 minute technical assessment: 1-800-301-3863

TECHNICAL SPECIFICATIONS





Battery+Motor Current Wheel Velocity Integrated GPS, Gyroscope and Accelerometer

SAMPLE APPLICATIONS

2.6 in

MULTI-ROBOT SYSTEMS

PERCEPTION & NAVIGATION

LAB TEACHING TOOL

Vbat (24V Norm) @ 20A

12V @ 10A



Jackal is engineered with a **scalable** and **open architecture** making it the ideal platform for testing and developing multi-robot systems.



Get your research rolling faster with **camera, GPS** and **laser packages**, all of which include documented libraries and programming examples.



Jackal is **lightweight, compact** and **easy to program** - the perfect platform to help build courseware that students will be excited about!

ENVIRONMENTAL MONITORING



Configure Jackal for teleoperation or autonomy in outdoor applications. The weatherproof, rugged chassis makes it ideal for environmental monitoring.

CONTACT US FOR MORE INFORMATION

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